

Kernel Bounds for Structural Parameterizations of Pathwidth

Bart M. P. Jansen

Joint work with Hans L. Bodlaender & Stefan Kratsch



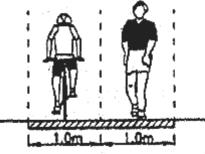
Universiteit Utrecht

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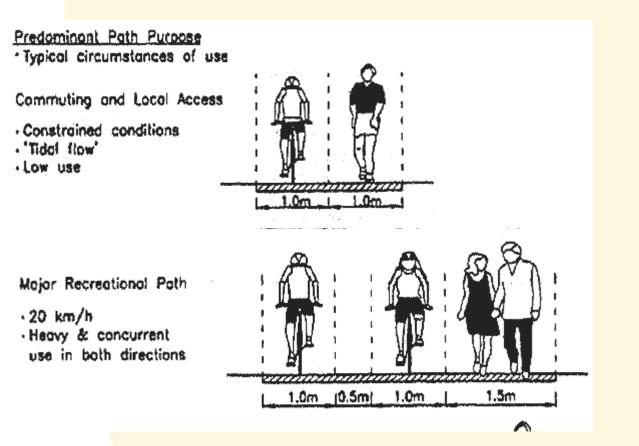




Predominant Path Purpose * Typical circumstances of use Commuting and Local Access • Constrained conditions • 'Tidal flow' • Low use







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Commuting and Local Acces - Constrained conditions - "Tidal flow" - Low use

Major Recreational Path

 20 km/h
 Heavy & concurrent use in both directions





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- Gives the quality of a path decomposition, a decomposition of a graph into pieces arranged on a path
- Both pathwidth and treewidth have been introduced many times under different names
 - (vertex separation number, node search number, partial k-tree, etc ...)
- Play crucial roles in Robertson & Seymour's proof of the Graph Minor Theorem



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 Many graph problems can be solved efficiently (in linear time) if a path or tree decomposition of small width is known



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- When comparing pathwidth to treewidth:
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 - Dynamic programming algorithms for path decompositions are simpler and use less memory
- Important to find low-width path and tree decompositions efficiently



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- Runtime $\mathfrak{S}(n)$ for every fixed k ٠



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- Cannot guarantee output is smaller than input (else P=NP)
- So given a graph G of "difficulty" k, shrink G to poly(k)
 - Afterwards we can shrink no more

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 - Unless NP \subseteq coNP/poly [BDFH'08,D'12]
 - k-Pathwidth is AND-compositional
- Pick a measure for graph difficulty that is larger than pw(G)
- Can we shrink to size polynomial in the larger measure?
 - For example: size of a minimum vertex cover
 - (Vertex set that covers all edges)





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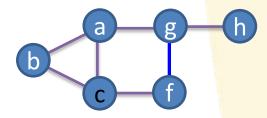
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- No prior work on preprocessing for pathwidth
- This work: reduction rules, analysis & lower bounds

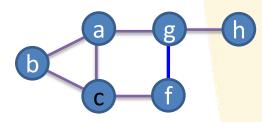






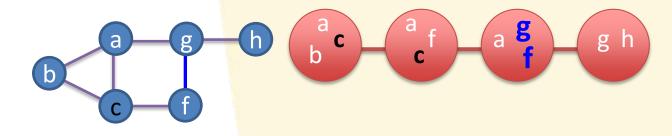


 A path decomposition of a graph G=(V,E) is a sequence (X₁, ..., X_r) of subsets of V, called **bags**, such that:



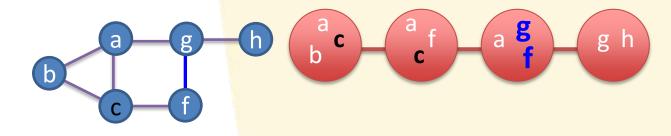


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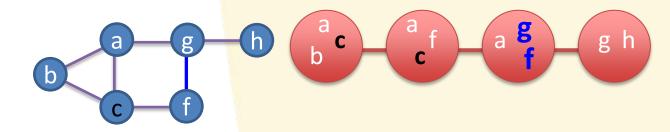


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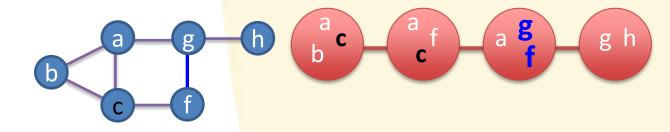


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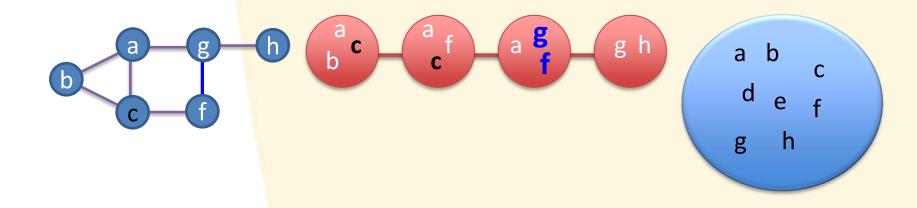


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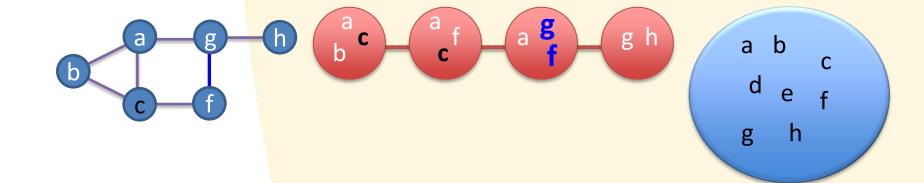




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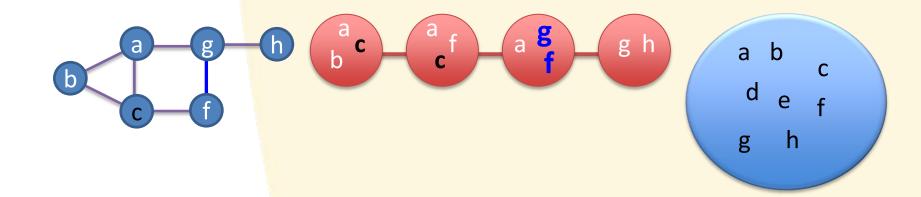






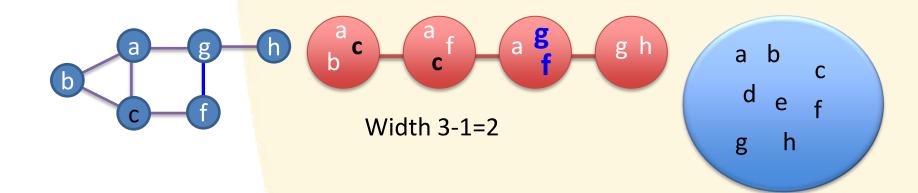


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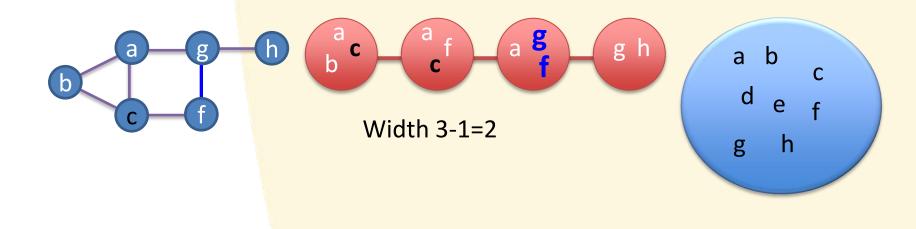


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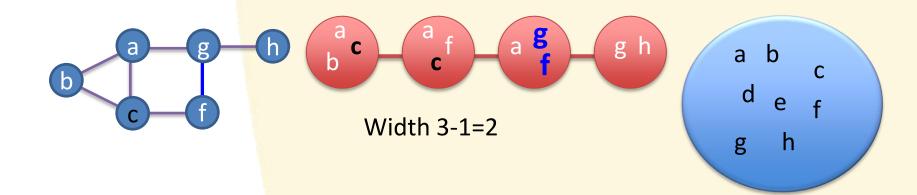


- The width of a path decomposition (X₁, ..., X_r) is the size of its largest bag minus one: max_{1≤i≤r} |X_i|-1
- The pathwidth of a graph G is the minimum width of a path decomposition of G



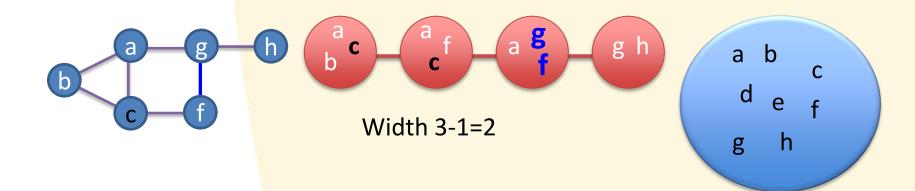


 Path/treewidth does not increase when deleting or contracting edges / vertices



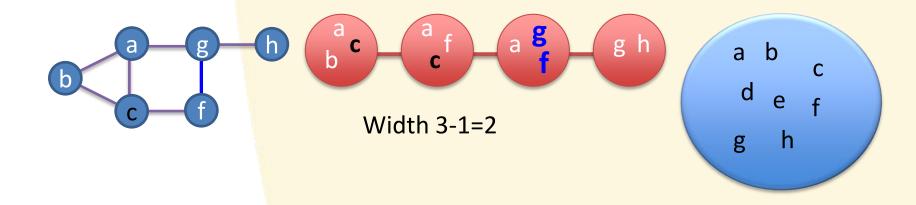


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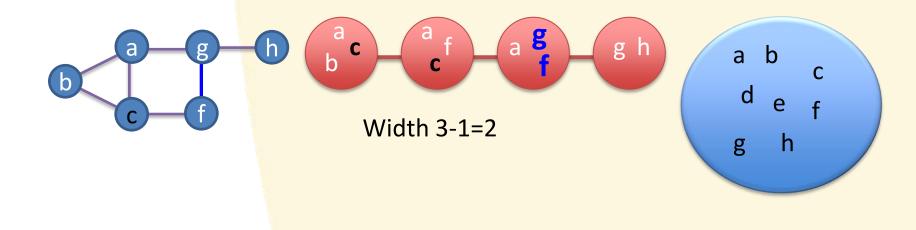


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- Path/treewidth does not increase when deleting or contracting edges / vertices
- Treewidth \leq pathwidth
- Paths have pathwidth = treewidth = 1
- Trees have treewidth 1, but may have pathwidth Θ(log n)





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- Easy to lift decompositions of G' to G
- In practical settings:
 - Guess k, or work with upper- and lower bounds





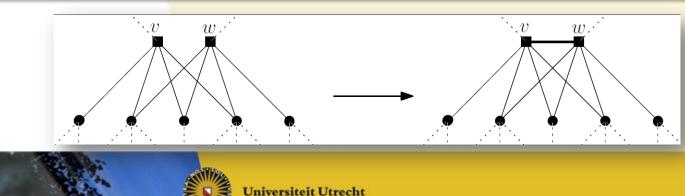
Treewidth Edge Improvement Rule

If v and w have $\geq k+1$ common neighbors in G, then adding edge {v,w} does not change whether tw(G) $\leq k$



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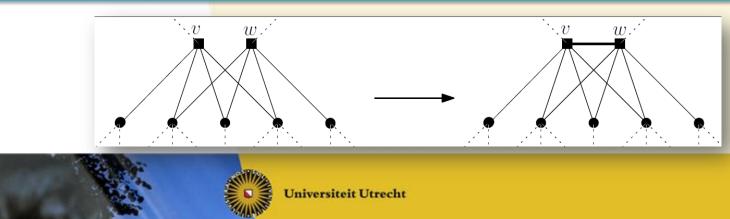
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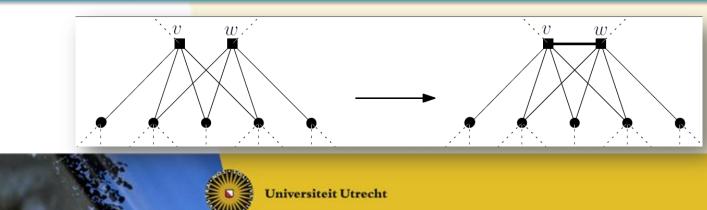
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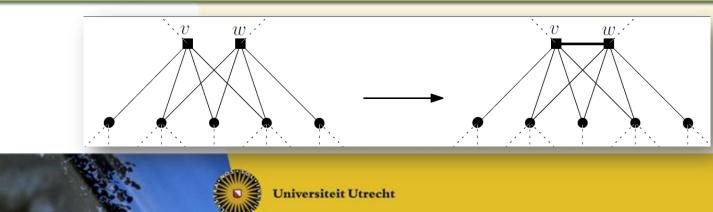
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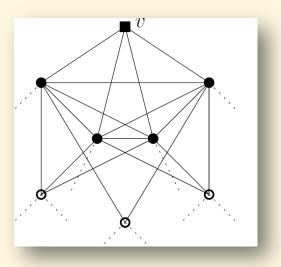




• A vertex v is simplicial if N(v) is a clique

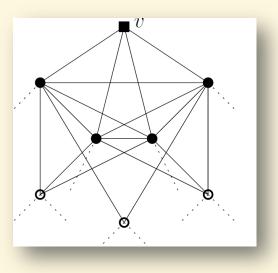


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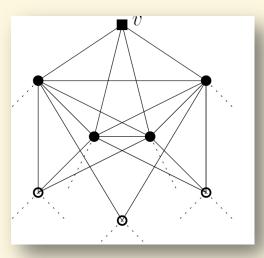


Treewidth Simplicial Vertex Rule

- If $deg(v) \ge k+1$ then tw(G) > k
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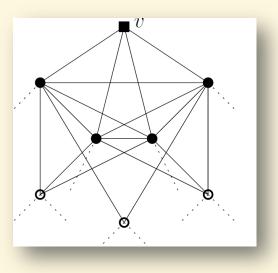
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Closed neighborhood of v is a k+2 clique

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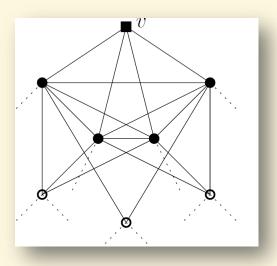


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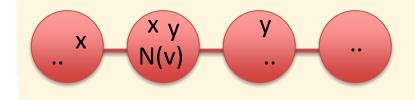


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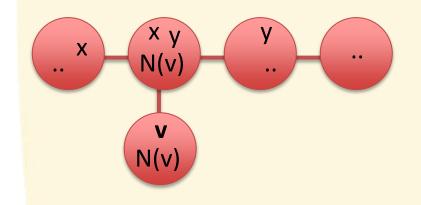


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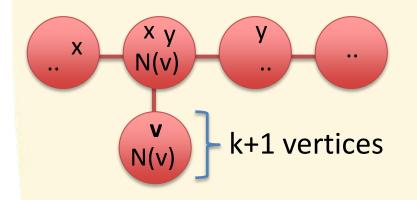


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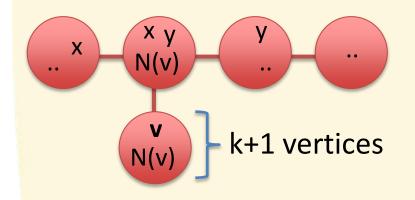


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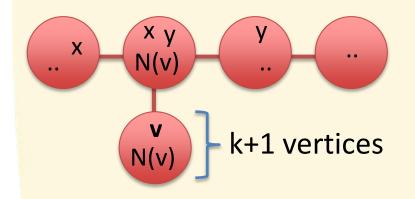




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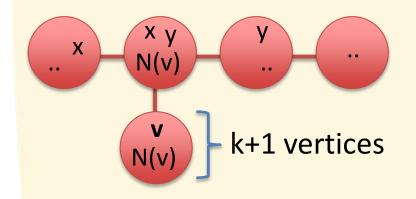


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Repeated application would eat up a tree

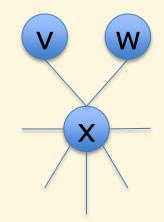
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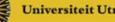
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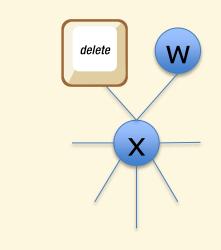




Pathwidth Degree-1 Vertex Rule

If vertex v is only adjacent to x, and there is another degree-1 vertex w adjacent to x, then then deleting v is safe for pathwidth k



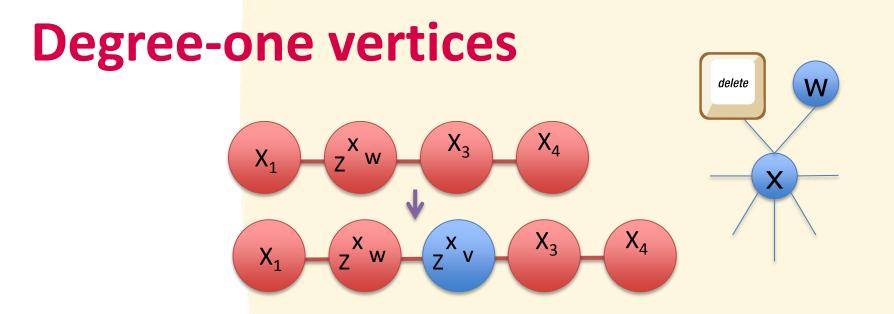


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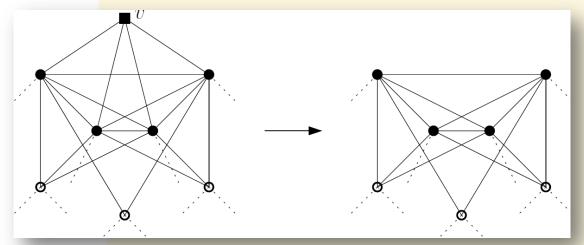
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If v is simplicial with $2 \le deg(v) \le k$, and $\forall \{x,y\}$ in N(v), \exists simplicial vtx \notin N[v] seeing x and y, then deleting v is safe for pathwidth k



Effects of the reduction rules

- If G has a vertex cover X of size *l*, and you work relative to the structure of X:
 - Easy counting arguments prove O(l³) vertices
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Polynomial kernels (sizes in # vertices)

- $O(\ell^3)$ when ℓ is the vertex cover number
- O(cl³ + c²l²) when l is the size of a vertex set whose removal gives components of at most c vertices each
- O(l⁴) when l is the size of a vertex set whose removal results in disjoint stars





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- We build a cross-composition of MinCut on cubic graphs into tree/pathwidth on a cobipartite graph where one partite set is small
 - Deleting the small set yields a clique

Details of the construction ...



Cutwidth crosscomposes into Tw by chique deletion. known: autwidth is NP-complete on planake marc. deg = 3 graphs. $n^2 > C(n+1)^k$ Poly equ: all input graphs have same degree sequence (charaderised by nª) and ask fore same R. Sort withins by degree. Assume n=3. $c(n+i)^{k} \leq c(2n)^{k}$ Typut instance on deg 53 graph has cutwidth </E133 B* SC.2 k. k. So 14 RS 32 Solectors n > c. 2 k. nk Set w:= 2n. we ark for (on small subinition a (U; U Bt); $C = n^{2-k} > C \cdot 2^{k}$ $C = n^{2-k} = (c \cdot 2^{k})^{2-k}$ n3(n+1)+le-1. So we ask in the big instance fore: 2 109 (t-1)n + n3(n+1)+le-1+2n logt = tn4 + n + /k - 1+2n log t. Zy now furement. f(n+1) = n2. 3-1 3-2 dy-3 After solving linetance we can oliminate the west, provided that f(n) = n. $f(n+1) = 2^{\lceil n \rceil} f(n+1)$ NS $le > (t - 1)n' - 1 + 2n(2 \log t) + 2(2) + n(n^3 - 1)$ n-1 n-2 n-3 = tn -1+4nlagt +2(2)-N. Last zien: Fly lyln+1) = (ly lyn) +1. n3 Edger he welen: lylghrildly lyn, en Lglg(n)%/100. We need: En +1 +1+21 log E> En 4-1+41 log E+2(2)-1 Ons The Lylner 17 3 La lyner. 四 … (2) n3+k-172nlat+2(2)-n-1 102 n3+le 32n logt+2(2)-n 12 Frould work if $n = \log t$: Here $2n \log t + 2(\frac{n}{2}) - n \leq 2n^2 + 2(\frac{n}{2}) - n \leq 2n^2 + \frac{2n(n-1)}{2} - n$ $3 2n^2 + n^2 = 3n^3$. So: $n^3 > 3n^2 < > n > 3$. $[A, l=n \cdot n^2 = n^4]$



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- Analysis proves effect of the rules with respect to several parameters
- Pathwidth and treewidth do not admit polynomial kernels by deletion distance to a clique



Future directions

Experimental evaluation of the reduction rules

Lower bounds on kernel sizes

• Kernel with $O(k^{3-\epsilon})$ bits for parameterization by vertex cover?

Pathwidth parameterized by feedback vertex set

- Polynomial kernel for treewidth by FVS
- Trees have constant treewidth but potentially large pathwidth



Future directions

Experimental evaluation of the reduction rules

THANK YOU!

Pathwidu

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