

# On Minimum Sum of Radii and Diameters Clustering

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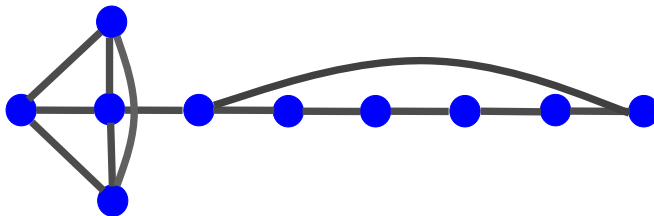
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- **Objective:** minimize  $\sum_{i=1}^k \text{rad}(V_i)$  in MSR, minimize  $\sum_{i=1}^k \text{diam}(V_i)$  in MSD.
- **Radius and Diameter:**  $\text{rad}(V_i) = \min_{u \in V_i} \max_{v \in V_i} d(u, v)$ ,  
 $\text{diam}(V_i) = \max_{u, v \in V_i} d(u, v)$

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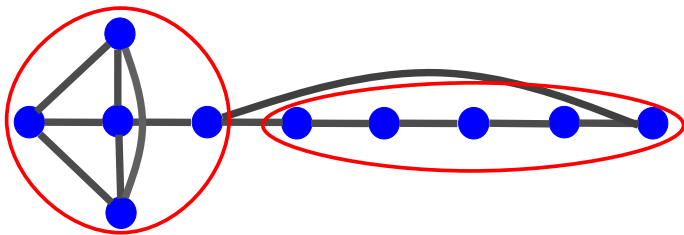
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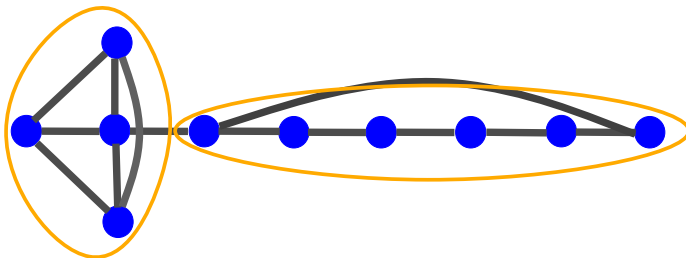


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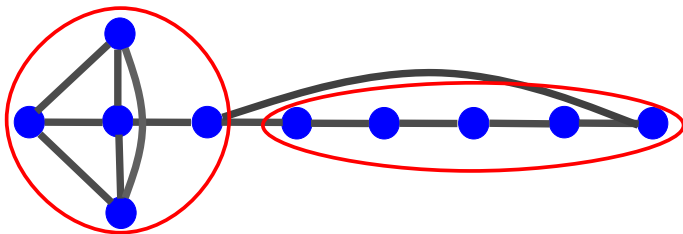


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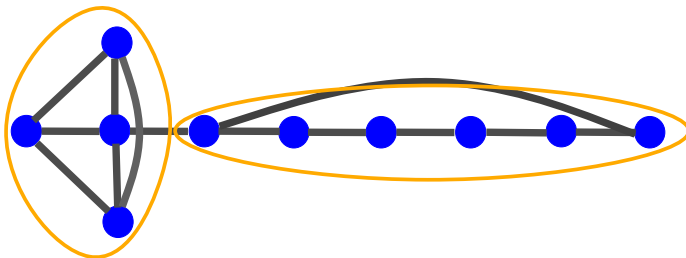


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## Clustering

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## Communication Networks

Location of base stations in a wireless data network.

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 $\rightarrow$  7.008-approximation for MSD
- exact algorithm for MSR in time  $n^{O(\log n \log \Delta)}$  where  $\Delta$  is the ratio of largest distance over the smallest distance (Gibson *et al.*, SWAT'08)  $\rightarrow$  QPTAS for MSR

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- Euclidean MSR: **exact** algorithm  $\rightarrow$  a **2**-approximation for Euclidean MSD. (Gibson *et al.*, SODA'08)

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Metrics with polynomially bounded  $\Delta$ : exact algorithm for MSR in time  $n^{O(\log^2 n)}$   $\rightarrow$  exact algorithm for MSR in this case?

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*There is a PTAS for the Euclidean MSD which runs in  $n^{O(1/\epsilon)}$*

# MSR Restricted to Unweighted Graphs

- Metric: the shortest path metric of an unweighted graph.

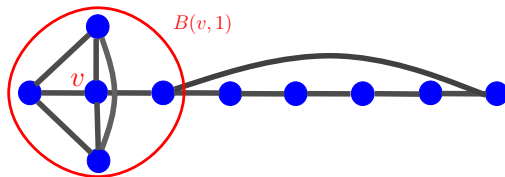
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- Metric: the shortest path metric of an unweighted graph.
- Solving MSR for the connected graphs → solve the general case.

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## Definition

$B(v, r)$  the set of vertices  $\{u \in V : d(v, u) \leq r\}$











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zero ball or singleton Ball of radius zero

two balls intersect At least one common vertex

two balls adjacent do not intersect and an edge connecting them

Canonical optimal solution has minimum number of balls

# Properties of a canonical optimal solution

## Lemma

*A canonical optimal solution does not have any intersecting balls.*

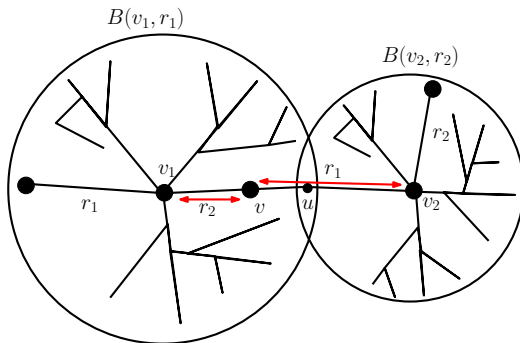


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**Proof:** Choose  $v$  at distance  $r_2$  from  $v_1$  on path  $v_1-v_2$ .



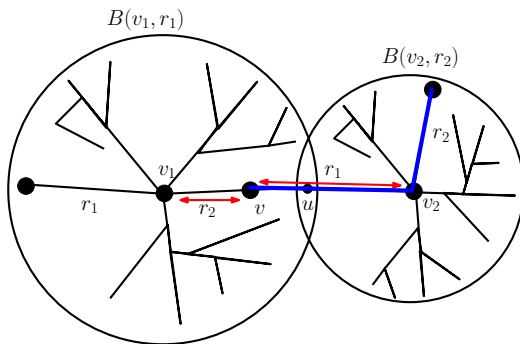


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*In a canonical optimal solution, each ball is adjacent to at most two balls. (Fails with existence of zero balls.)*





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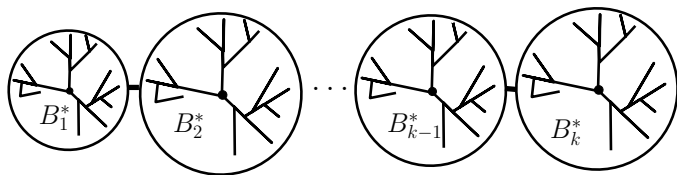
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- Consider a canonical optimal solution:  $B_1^*, B_2^*, \dots, B_k^*$ .



# General Idea

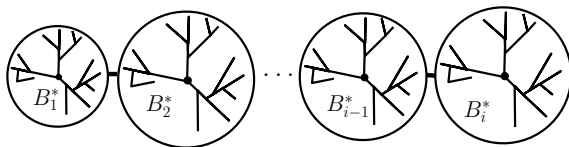
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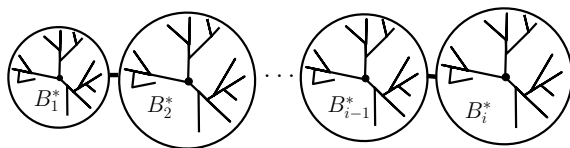
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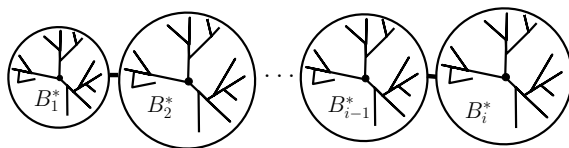
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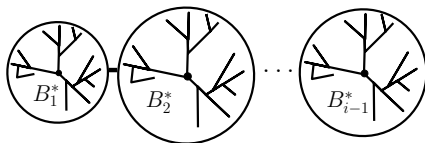
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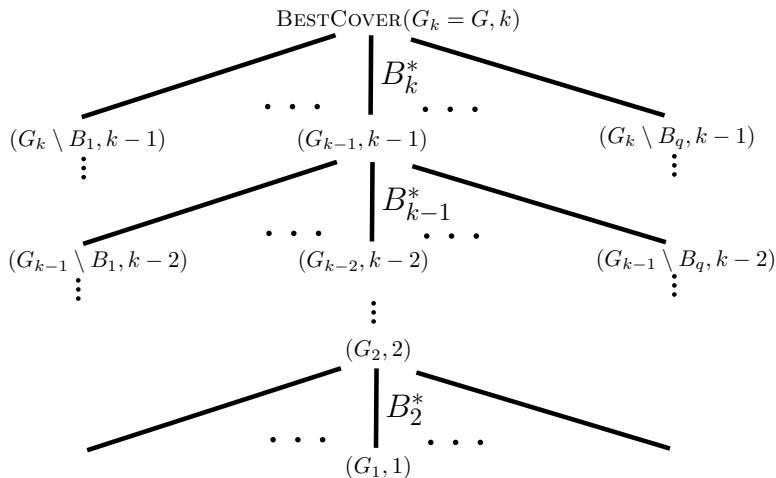
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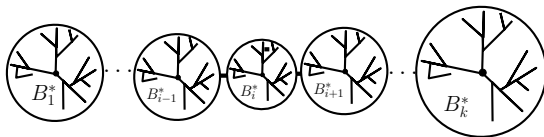
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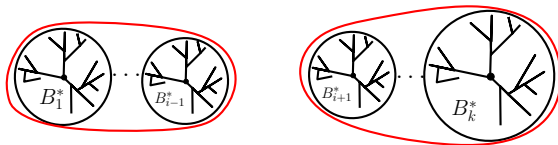
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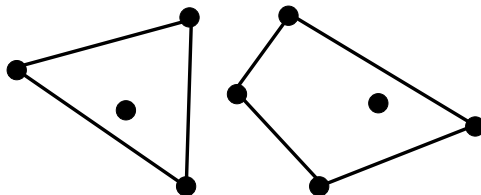
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- Recursively solve each part using dynamic programming.

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- **Intuitive Example:** A regular polygon and the polygon constructed from extension of every  $i$ th edges of it

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A PTAS for the general version?
- We gave a PTAS for Euclidean MSD. The complexity of Euclidean MSD?
- The MSD problem with constant  $k$ : we found an exact algorithm.

**Thanks for your attention!**  
**Questions?**